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Feedback controller, which provides stabilization of the object around the nominal trajectory, can be designed using linearized model. Under assumption that the dynamic behavior of the object with ...

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control laws can be designed. This is followed in Chapter 7 by material on output feedback and estimators. Chapters 6 and 7 introduce the key concepts of reachability and observability, which give tremendous insight into the choice of actuators and sensors, whether for engineered or natural systems.

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GMT feedback control of dynamic systems pdf - Feedback occurs when outputs of a system are routed back as inputs as part of a chain of cause-and-effect that forms a circuit or loop. The system can then be said to feed back into itself. The notion of cause-and-effect has to be handled carefully

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